

Uitwerking Final Exam

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(2/1)

Working this out gives

$$\begin{cases} \varphi_1(0) = \varphi_2(0) \\ \frac{\partial \varphi_1(0)}{\partial x} = \frac{\partial \varphi_2(0)}{\partial x} \end{cases} \Rightarrow \begin{cases} A + B = C \\ k_1 \cdot A - k_1 \cdot B = k_2 \cdot C \end{cases} \Rightarrow$$

a) Time-independent Schrödinger equation for a one-dimensional particle, in x -representation:

$$\left[-\frac{\hbar^2}{2m} \frac{\partial^2}{\partial x^2} + V(x) \right] \varphi(x) = E \varphi(x) \quad \Rightarrow$$

$$\frac{\partial^2}{\partial x^2} \varphi(x) = -\frac{2m(E-V)}{\hbar^2} \varphi(x)$$

This differential equation has solutions of the form $\varphi(x) = e^{ikx}$ (plane waves with wave number k)

This is consistent with the Schrödinger equation for

$$R = \frac{\sqrt{2m(E-V)}}{\hbar} \quad \Rightarrow \quad k_i = \frac{\sqrt{2m(E-V_i)}}{\hbar}$$

b) During the scatter event $\varphi(x)$ should have $\varphi(x)$

$\frac{\partial \varphi}{\partial x}$ continuous at $x=0$, where $\varphi(x)$ the wavefunction of the particle. Here $\varphi(x)$ is:

$$\text{In region 1, } \varphi(x) = \varphi_1(x) = A e^{ik_1 x} + B e^{-ik_1 x}$$

(an incoming and reflected plane wave)

$$\text{In region 2, } \varphi(x) = \varphi_2(x) = C e^{ik_2 x}$$

(only a transmitted plane wave)

A description of these plane waves only is appropriate because the uncertainty in velocity is very small.

Only differences in energy matter, absolute values of energy have little meaning.

d) Use c) and substitute

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Problem 2

(i)

a) Normalized if $\int_{-\infty}^{\infty} |\psi(x)|^2 dx = 1$

$$\begin{array}{c|c|c|c} \text{case} & (E_0 - V_1) & V_0 & R \\ \hline V_2 = 0.5 V_1 & V_1 & 0.5 V_1 & 0.01 \\ V_2 = 1 V_1 & V_1 & 0 & 0 \\ V_2 = 1.5 V_1 & V_1 & -0.5 V_1 & 0.029 \end{array}$$

b) Answer is $\psi(k)$ in k -representation \Rightarrow

$$\boxed{V_2 = 0.5 V_1} \quad R = \frac{1 - \sqrt{1.5}}{1 + \sqrt{1.5}} \approx 0.01$$

$$\boxed{V_2 = V_1} \quad R = \left| \frac{1 - \sqrt{1}}{1 + \sqrt{1}} \right|^2 = 0$$

$$\boxed{V_2 = 1.5 V_1} \quad R = \left| \frac{1 - \sqrt{0.5}}{1 + \sqrt{0.5}} \right|^2 \approx 0.029$$

$$\begin{aligned} \bar{\psi}(k) &= \frac{1}{\sqrt{2\pi}} \int_{-\infty}^{\infty} \psi(x) e^{-ikx} dx \\ &= \frac{A}{\sqrt{2\pi}} \int_{-\infty}^0 e^{(\frac{1}{a} - ik)x} dx + \frac{A}{\sqrt{2\pi}} \int_0^{\infty} e^{-(\frac{1}{a} + ik)x} dx \\ &= \frac{A}{\sqrt{2\pi}} \frac{1}{(\frac{1}{a} - ik)} \left[e^{(\frac{1}{a} - ik)x} \right]_0^{\infty} + \frac{A}{\sqrt{2\pi}} \frac{-1}{(\frac{1}{a} + ik)} \left[e^{-(\frac{1}{a} + ik)x} \right]_0^{\infty} \\ &= \frac{A}{\sqrt{2\pi}} \frac{1}{\frac{1}{a} - ik} (1 - 0) + \frac{A}{\sqrt{2\pi}} \frac{-1}{\frac{1}{a} + ik} (0 - 1) \\ &= \frac{A}{\sqrt{2\pi}} \left(\frac{1}{\frac{1}{a} - ik} + \frac{1}{\frac{1}{a} + ik} \right) = \frac{A}{\sqrt{2\pi}} \left(\frac{\frac{1}{a} + ik}{\frac{1}{a^2} + k^2} + \frac{\frac{1}{a} - ik}{\frac{1}{a^2} + k^2} \right) \\ &= \frac{A}{\sqrt{2\pi}} \left(\frac{2}{\frac{1}{a^2} + k^2} \right) = \frac{2\alpha A}{\sqrt{2\pi}} \cdot \frac{1}{1 + \alpha^2 k^2} \Rightarrow \text{with } A = \frac{1}{\sqrt{a}} \end{aligned}$$

$$\bar{\psi}(k) = \frac{2\sqrt{a}}{\sqrt{2\pi}} \cdot \frac{1}{1 + \alpha^2 k^2}$$

$\rightarrow \Delta x:$

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d) Velocity is proportional to k , $v = \frac{p_x}{m} = \frac{\hbar k}{m} \Rightarrow$

Use k -representation to evaluate this probability

$$P_{k_{50}} = \int_{k_{40}}^{k_{50}} |\langle \psi(k) \rangle|^2 dk = \int_{k_{40}}^{k_{50}} \left(\frac{2k}{2\pi} \right)^2 \left(\frac{1}{1+a^2 k^2} \right)^2 dk$$

$$\langle \psi(k) \rangle \text{ drops to } \frac{1}{2} A \text{ for } k = \pm \frac{1}{a} \Rightarrow \text{Width of this state } \approx a \Rightarrow \Delta x \approx a$$

$$= \frac{2a}{\pi} \int_{k_{40}}^{k_{50}} \left(\frac{1}{1+a^2 k^2} \right) dk = \frac{2a}{\pi} \left[\frac{1}{2} \frac{k}{1+a^2 k^2} + \frac{1}{2} \frac{\arctan(ak)}{a} \right]_{k_{40}}^{k_{50}}$$

$$\Delta p_x:$$

$$= \frac{1}{\pi} \left[\frac{ak}{1+a^2 k^2} + \arctan(ak) \right]_{k_{40}}^{k_{50}}, \quad \text{with}$$

$$ak_{40} = \frac{\alpha m v_{40}}{\hbar} = \frac{1 \cdot 10^{-9} \cdot 91 \cdot 10^{-31} \cdot 40 \cdot 10^3 \text{ m kg/s}}{1.055 \cdot 10^{-34} \text{ Js}} = 0.345$$

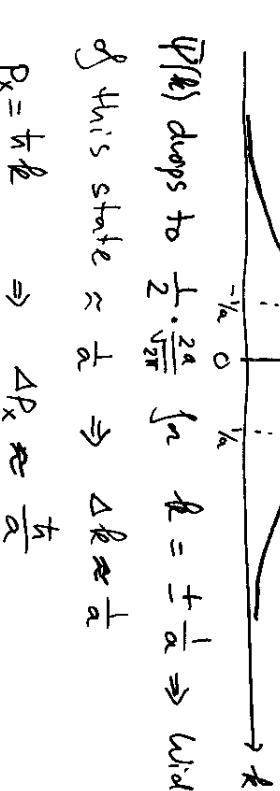
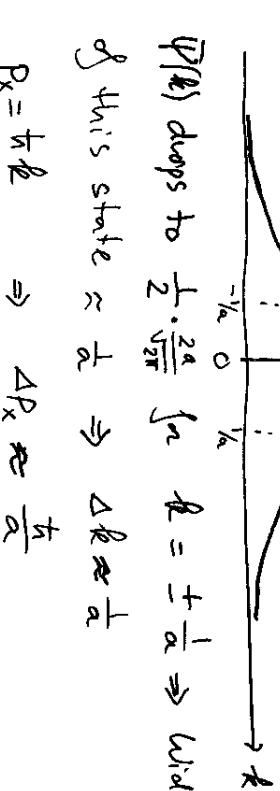
$$ak_{50} = \frac{\alpha m v_{50}}{\hbar} = \frac{1 \cdot 10^{-9} \cdot 91 \cdot 10^{-31} \cdot 50 \cdot 10^3 \text{ m kg/s}}{1.055 \cdot 10^{-34} \text{ Js}} = 0.431$$

$$\langle \psi(k) \rangle \text{ drops to } \frac{1}{2} \cdot \frac{2a}{\sqrt{2\pi}} \text{ for } k = \pm \frac{1}{a} \Rightarrow \text{Width of this state } \approx a \Rightarrow \Delta k \approx \frac{1}{a}$$

$$\Rightarrow P_{k_{50}} = \frac{1}{\pi} \left(\frac{0.431}{1+(0.431)^2} - \frac{0.345}{1+(0.345)^2} + \arctan(0.431) - \arctan(0.345) \right)$$

$$Heisenberg: \Delta x \Delta p_x \geq \frac{\hbar}{2}$$

Here we find $\Delta x \cdot \Delta p_x \approx a \cdot \frac{1}{a} \approx \hbar \Rightarrow \text{No violation}$



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Problem 3

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c) For \hat{H}_0 :

$$[\hat{A}, \hat{H}_0] = \hat{A}\hat{H}_0 - \hat{H}_0\hat{A} = \begin{pmatrix} -\alpha & 0 \\ 0 & \alpha \end{pmatrix} \begin{pmatrix} E_0 & 0 \\ 0 & E_0 \end{pmatrix} - \begin{pmatrix} E_0 & 0 \\ 0 & E_0 \end{pmatrix} \begin{pmatrix} -\alpha & 0 \\ 0 & \alpha \end{pmatrix}$$

in the Schrödinger equation $\hat{H}/|\psi_i\rangle = E_i/|\psi_i\rangle$
 For $\begin{pmatrix} \frac{1}{\sqrt{2}} \\ \frac{1}{\sqrt{2}} \end{pmatrix}$ this gives

$$\begin{pmatrix} E_0 & T \\ T & E_0 \end{pmatrix} \begin{pmatrix} \frac{1}{\sqrt{2}} \\ \frac{1}{\sqrt{2}} \end{pmatrix} = E_0 \begin{pmatrix} \frac{1}{\sqrt{2}} \\ \frac{1}{\sqrt{2}} \end{pmatrix} \Rightarrow E_0 = E_0 + T$$

For $\begin{pmatrix} \frac{-1}{\sqrt{2}} \\ \frac{1}{\sqrt{2}} \end{pmatrix}$ this gives

$$\begin{pmatrix} E_0 & T \\ T & E_0 \end{pmatrix} \begin{pmatrix} \frac{-1}{\sqrt{2}} \\ \frac{1}{\sqrt{2}} \end{pmatrix} = E_0 \begin{pmatrix} \frac{-1}{\sqrt{2}} \\ \frac{1}{\sqrt{2}} \end{pmatrix} \Rightarrow E_0 = E_0 - T$$

Given that T real and $T < 0$, it must be that

$$\left\{ \begin{array}{l} E_g = E_+ = E_0 + T, \text{ for } |\psi_g\rangle \\ E_e = E_- = E_0 - T, \text{ for } |\psi_e\rangle \end{array} \right.$$

b) $\langle \psi_g | \psi_g \rangle = (\frac{1}{\sqrt{2}} \frac{1}{\sqrt{2}}) \begin{pmatrix} \frac{1}{\sqrt{2}} \\ \frac{1}{\sqrt{2}} \end{pmatrix} = \frac{1}{2} + \frac{1}{2} = 1 \Rightarrow \text{Normalized}$

$$\langle \psi_e | \psi_e \rangle = (\frac{1}{\sqrt{2}} \frac{-1}{\sqrt{2}}) \begin{pmatrix} \frac{1}{\sqrt{2}} \\ \frac{-1}{\sqrt{2}} \end{pmatrix} = \frac{1}{2} + \frac{1}{2} = 1 \Rightarrow \text{Normalized}$$

$$\langle \psi_e | \psi_g \rangle = (\frac{1}{\sqrt{2}} \frac{-1}{\sqrt{2}}) \begin{pmatrix} \frac{1}{\sqrt{2}} \\ \frac{1}{\sqrt{2}} \end{pmatrix} = \frac{1}{2} - \frac{1}{2} = 0 \Rightarrow \text{Orthogonal}$$

\Rightarrow eigenvalue $-\alpha$ has eigenvector $|\psi_L\rangle$

d) \hat{A} is a diagonal matrix, so the eigenvalues are on the diagonal.
 \hat{H}_0 and \hat{A} commute (but \hat{H}_0 degenerate), so the eigenvectors of \hat{A} are the same or a linear superposition of those of \hat{H}_0 .

$$\hat{A}|\psi_i\rangle = \pm \alpha |\psi_i\rangle \Rightarrow$$

$$\begin{pmatrix} -\alpha & 0 \\ 0 & \alpha \end{pmatrix} \begin{pmatrix} 0 \\ 1 \end{pmatrix} = \pm \alpha \begin{pmatrix} 0 \\ 1 \end{pmatrix} \text{ is consistent for } |\psi_i\rangle \Leftrightarrow \begin{pmatrix} 0 \\ 1 \end{pmatrix}$$

\Rightarrow eigenvalue $\pm \alpha$ has eigenvector $|\psi_i\rangle$

$$\begin{pmatrix} -\alpha & 0 \\ 0 & \alpha \end{pmatrix} \begin{pmatrix} 1 \\ 0 \end{pmatrix} = -\alpha \begin{pmatrix} 1 \\ 0 \end{pmatrix} \text{ is consistent for } |\psi_i\rangle \Leftrightarrow \begin{pmatrix} 1 \\ 0 \end{pmatrix}$$

e) Ground state of \hat{H} is $|q_g\rangle = \frac{1}{\sqrt{2}}(|q_L\rangle + |q_R\rangle)$ (9/11)

So, a measurement of \hat{A} can gives both $+a$ and $-a$ as answer

Measurement outcome	Probability	State after measurement
$-a$	$ \langle q_L q_g \rangle ^2 = \frac{1}{2}$	$ q_L\rangle$
$+a$	$ \langle q_R q_g \rangle ^2 = \frac{1}{2}$	$ q_R\rangle$

$$f) |\psi\rangle = \sqrt{\frac{1}{3}}|q_g\rangle + \sqrt{\frac{2}{3}}|q_e\rangle = \left(\sqrt{\frac{1}{6}}|q_L\rangle + \sqrt{\frac{1}{6}}|q_R\rangle\right) + \left(\sqrt{\frac{2}{6}}|q_L\rangle - \sqrt{\frac{2}{6}}|q_R\rangle\right)$$

$$= \frac{1+\sqrt{2}}{\sqrt{6}}|q_L\rangle + \frac{1-\sqrt{2}}{\sqrt{6}}|q_R\rangle \Rightarrow \text{Both } |q_L\rangle \text{ and } |q_R\rangle$$

have non-zero probability amplitude, so a measurement can give both $+a$ and $-a$ as answer.

Probability for $-a$ is $|\langle q_L | \psi \rangle|^2$, for $+a$ is $|\langle q_R | \psi \rangle|^2$,

Measurement outcome	Probability	State after measurement
$-a$	$\left(\frac{1+\sqrt{2}}{\sqrt{6}}\right)^2$	$ q_L\rangle$
$+a$	$\left(\frac{1-\sqrt{2}}{\sqrt{6}}\right)^2$	$ q_R\rangle$

1

g) The state is $|q_L\rangle = \frac{1}{\sqrt{2}}(|q_g\rangle + |q_e\rangle)$ (10/11)

since $|q_g\rangle = \frac{1}{\sqrt{2}}(|q_L\rangle + |q_R\rangle)$ and $|q_e\rangle = \frac{1}{\sqrt{2}}(|q_L\rangle - |q_R\rangle)$

$$h) \langle q_g | \hat{A} | q_g \rangle = \left(\frac{1}{\sqrt{2}} \frac{1}{\sqrt{2}}\right) \begin{pmatrix} -a & 0 \\ 0 & a \end{pmatrix} \begin{pmatrix} \frac{1}{\sqrt{2}} \\ \frac{1}{\sqrt{2}} \end{pmatrix} = 0 \Rightarrow \text{expectation value}$$

for position is zero for system in state $|q_g\rangle$

$$\langle q_e | \hat{A} | q_e \rangle = \left(\frac{1}{\sqrt{2}} \frac{-1}{\sqrt{2}}\right) \begin{pmatrix} -a & 0 \\ 0 & a \end{pmatrix} \begin{pmatrix} \frac{1}{\sqrt{2}} \\ \frac{1}{\sqrt{2}} \end{pmatrix} = 0 \Rightarrow \text{expectation value for position is zero for system in state } |q_e\rangle$$

$$\langle q_g | \hat{A} | q_e \rangle = \left(\frac{1}{\sqrt{2}} \frac{1}{\sqrt{2}}\right) \begin{pmatrix} -a & 0 \\ 0 & a \end{pmatrix} \begin{pmatrix} \frac{1}{\sqrt{2}} \\ \frac{1}{\sqrt{2}} \end{pmatrix} = -a$$

when the system is in a superposition of $|q_g\rangle$ and $|q_e\rangle$

$$\langle q_e | A | q_g \rangle = \left(\frac{1}{\sqrt{2}} \frac{-1}{\sqrt{2}}\right) \begin{pmatrix} -a & 0 \\ 0 & a \end{pmatrix} \begin{pmatrix} \frac{1}{\sqrt{2}} \\ \frac{1}{\sqrt{2}} \end{pmatrix} = -a$$

the expectation value for position can be different from zero.

i) State at $t=0$ denoted as $|q_0\rangle = |q_L\rangle = \frac{1}{\sqrt{2}}(|q_g\rangle + |q_e\rangle)$

For investigating time evolution of \hat{A} describe the state of the system as a superposition of energy eigen states.

$$\langle \hat{A}(t) \rangle = \langle \psi(t) | \hat{A} | \psi(t) \rangle = \langle q_0 | I + \hat{A}^{\dagger} \hat{A} | q_0 \rangle$$

$$\text{with } I = e^{-\frac{i}{\hbar} \hat{H} t} \Rightarrow$$

(10/11)

$$\langle \hat{A}(t) \rangle = \frac{1}{2} (\langle \varphi_g | + \langle \varphi_e |) \hat{a}^\dagger \hat{A} \hat{a} (\langle \varphi_g | + \langle \varphi_e |)$$

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=

$$= \frac{1}{2} \left(e^{+i\omega_g t} \langle \varphi_g | + e^{+i\omega_e t} \langle \varphi_e | \right) \hat{A} \left(e^{-i\omega_g t} \langle \varphi_g | + e^{-i\omega_e t} \langle \varphi_e | \right)$$

$$= \frac{1}{2} \left(\langle \varphi_g | \hat{A} | \varphi_g \rangle + \langle \varphi_e | \hat{A} | \varphi_e \rangle + e^{+i(\omega_g - \omega_e)t} \langle \varphi_g | \hat{A} | \varphi_e \rangle + e^{+i(\omega_e - \omega_g)t} \langle \varphi_e | \hat{A} | \varphi_g \rangle \right)$$

$$= \frac{1}{2} \left(0 + 0 + e^{-i(\omega_e - \omega_g)t} (-\alpha) + e^{+i(\omega_e - \omega_g)t} (\alpha) \right)$$

$$= -\frac{1}{2} \alpha \cdot 2 \cos((\omega_e - \omega_g)t)$$

$$= -\alpha \cos((\omega_e - \omega_g)t)$$

Where we used $\omega_e = \frac{E_e}{\hbar}$ and $\omega_g = \frac{E_g}{\hbar}$

$$E_e - E_g = \underbrace{-2T}_{>0} \Rightarrow$$

$$\langle \hat{A}(t) \rangle = -\alpha \cos\left(\frac{12\pi}{\hbar}t\right)$$

The system oscillates between the two walls, from position $-\alpha$ to α and back, and starts (as it should) indeed at $-\alpha$ for $t=0$.

The frequency of the oscillations is $\frac{E_e - E_g}{\hbar} = \frac{12T}{\hbar}$

angular